

[45] CT-FEM Opera iii (Stress analysis)
English version

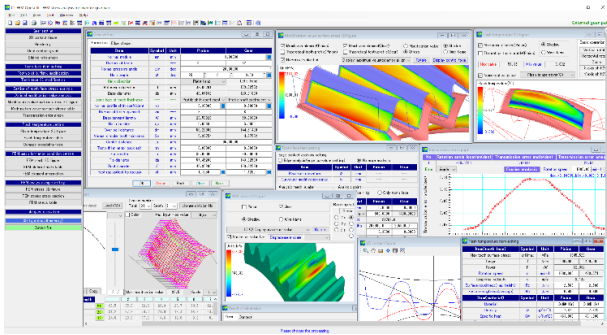
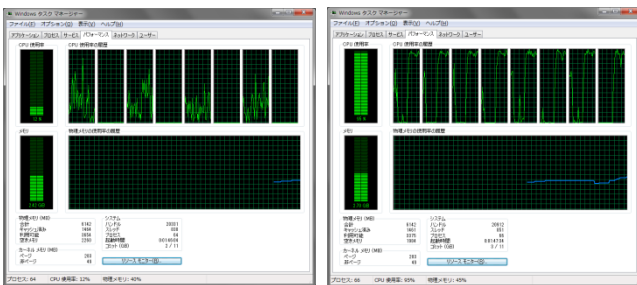


Fig.45.1 CT-FEM Opera iii

45.1 Abstract

The CT-FEM Opera which was developed in 2014 is the software which has a lot of results, doing much verification. In this time, we developed new CT-FEM Opera iii (includes a parallel processing feature), doing based on the CT-FEM Opera. For example, when analyzing a helical gear ($m_n=2, z_1=z_2=20, \alpha=20^\circ, \beta=11^\circ, b_1=b_2=10$) in 3D-FEM (elements =18335, nodes = 29638), the computing time of the CT-FEM Opera is 105 seconds but in CT-FEM Opera iii, it is 13.7 seconds (Microsoft Surface Pro3, CPU: Intel® Core™ i7-4650U, Memory, 8.0GB).



(a) not parallel processing (b) parallel processing
Fig.45.2 CPU system operating status (Task Manager)

The CT-FEM Opera iii enriches a tooth surface analysis. The contents can be computed in the flash temperature, the friction coefficient, the oil film thickness, the transmission error analysis, Fourier analyses, scuffing probability and then the lifetime time, too. Also, it is adding an edge contact analysis and a best tooth surface formation analysis (tooth surface stress minimum value), too. Therefore, the damage by the trochoid interference and the noise can do the tooth surface retouch which is proper for the occurring gear.

Then, the stress change at the rotation angle can be observed by the animated feature. Therefore, because the stress distribution phenomenon can be easily grasped when analyzing by the specification of the gear which the damage occurred to, it is very valid with the improvement of the present situation gear and the explanation to the user.

Moreover, the beginner can use easily because the explanation is displayed by pushing [F1] key if there are unclear contents when using software. Fig.45.1 shows the whole screen.

See by all means because the analysis and the transmission error analysis of the tooth surface damage experiment are shown to the appendix [I], [J].

45.2 Software structure

The structure of CT-FEM Opera iii is shown in Table 45.1. ○ in the table is included in the basic software, and ⊙ is optional. Applicable gear: involute spur and helical gear (external gear, internal gear)

Table 45.1 software structure

Item	Structure
<1>Basic rack	○
<2>Gear dimension	○
<3>Meshing drawing	○
<4>Tooth modification	○
<5>Tooth surface stress distribution (3D)	○
<6>Tooth surface evaluation ⁽¹⁾ friction coefficient, oil film thickness, calorific potential, Power loss PV value, PVT value	○
<7>Scuffing probability of occurrence ⁽¹⁾	○
<8>Abrasion probability of occurrence ⁽¹⁾	○
<9>Life time ⁽¹⁾	○
<10>Power loss ⁽¹⁾	○
<11>3D-FEM	○
<12> Edge contact analysis	⊙
<13>Transmission analysis, Fourier analyses, CSV	⊙
<14>Internal gear	⊙
<15>Best tooth surface modification	⊙
<16>Tooth profile data(3D-IGES)	⊙

(1) Doesn't support a plastic gear

45.3 Property (Basic rack)

A setting screen is shown to Fig.45.3.

- Gear combination : external × external, external × internal
- Basic rack : standard, low, special
- tooth tip circle decision : normal, equal clearance
- center distance and shift coefficient
- The switch which makes parallel processing valid
- The switch to consider the influence of the profile deviation

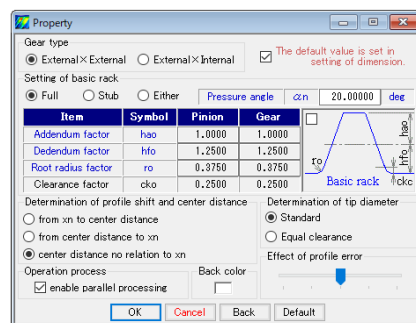


Fig.45.3 property (basic rack)

45.4 Gear dimension

Gear dimension calculates parts dimensions, contact ratio, sliding ratio, tooth thickness and so on. The gear with undercut determines the contact rate based on the TIF (True Involute Form) diameter. If tooth tip is rounded, R and C is considered in contact ratio.

(1) center distance and shift coefficient have the following 3 relationships.

<1> shift coefficient is given to pinion and gear to determine center distance.

<2> based on center distance, shift coefficient of each gear is determined.

<3> center distance is set, regardless of shift coefficient.

(2) shift coefficient is set per following 4 types;

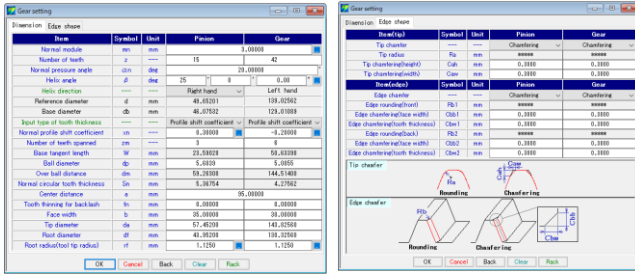
<1> directly enter shift coefficient

<2> based on split tooth thickness, shift coefficient is set

<3> based on over pin dimension, shift coefficient is set

<4> based on arc tooth thickness, shift coefficient is set

Dimension setup screen is shown in Fig.45.4 Shift coefficient can be set by tooth thickness. See Fig.45.6 for dimension result.



(a) gear dimension

(b) chamfering

Fig.45.4 gear specification

Item	Symbol	Unit	Pinion	Gear
Transverse module	mt	mm		3.31013
Transverse pressure angle	α_t	deg		21.88023
Base helix angle	β_b	deg		23.38886
lead	pz	mm	334.5139	936.6388
Profile shift coefficient	xm	mm	0.3000	-0.6000
Tooth depth	h	mm	6.7500	6.7500
Min involute diameter(TIP)	dt	mm	46.6316	133.0264
Max involute diameter	dh	mm	56.8520	143.2256
Transverse pitch	pbt	mm		9.6500
Transverse circular tooth thickness	st	mm	5.9224	4.7176
Number of teeth spanned	zm	---	3	6
Base tangent length(Reference)	w	mm	23.59028	50.63398
Base tangent length(Design)	w'	mm	23.59028	50.63398
Over ball diameter	dp	mm	5.6039	5.0055
Over ball diameter(Reference)	dm	mm	59.28308	144.51400
Over ball diameter(Design)	dm'	mm	59.28322	144.51390

Fig.45.5 dimension result-1

Item	Symbol	Unit	Pinion	Gear
Transverse contact module	$\alpha_w t$	deg		22.85269
Contact helix angle	β_w	deg		25.15362
Contact pitch diameter	dw	mm	50.0000	140.0000
teeth number ratio	zh	---	2.8000	0.3571
Effective face width	bw	mm		30.0000
Clearance	ck	mm	1.1112	1.1112
Transverse contact ratio	ϵ_α	---		1.1256
Overlap ratio	ϵ_β	---		1.3452
Total contact ratio	ϵ_γ	---		2.4708
Sliding ratio(tip)	σ_a	---	0.5858	0.4787
Sliding ratio(root)	σ_b	---	-0.9183	-1.3035
Transverse backlash	Jt	mm		0.2797
backlash angle	J θ	deg	0.69561	0.24843
Contact diameter(max)	dja	mm	56.8520	143.2256
Contact diameter(min)	djf	mm	47.5086	135.2138

Fig.45.6 dimension result-2

45.5 Tooth profile and rendering

Meshing drawing is shown in Fig.45.7. As shown in support form, zoom, distance measurement, R-measurement, diameter, involute modification, line of action, display and rotation function are available. And a rendering is shown in Fig.45.8.

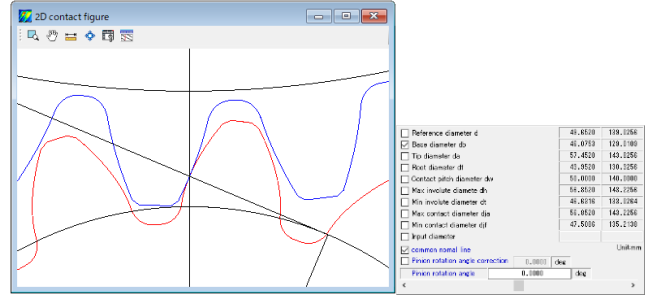


Fig.45.7 meshing drawing & support form

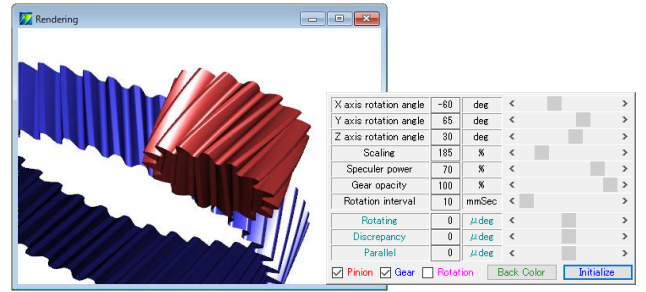


Fig.45.8 tooth profile rendering & support form

45.6 Contact line and sliding ratio graph

The contact line graph is shown in Fig.45.8. This graph shows the relation of the meshing well because the line of action length of the gear is shown in the vertical axis with the line of action length of the pinion shown in the transverse. In the Fig.45.9, when the contact diameter of the pinion is 50.030 mm, the contact diameter of the gear is 139.969 mm. Also, the line of action length of this pinion is 9.749.657 mm and the gear is 27.145 mm.

Moreover, the meshing of the tooth can be grasped because are connected with contact profile (Fig.45.7). The rotation angle computation (Fig.45.10) is the auxiliary calculation function to compute relation between the contact diameter, the line of action length and the roll angle and then the rotation angle. And, the sliding ratio graph is shown in Fig.45.11.

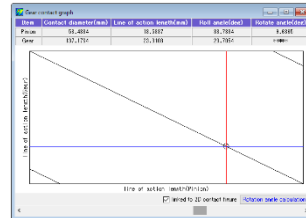


Fig.45.9 contact line

Item	Symbol	Unit	Pinion	Gear
Contact diameter	d	mm	51.0000	142.3333
Line of action length	L	mm	10.9923	25.8622
Roll angle	ϕ	deg	27.1893	23.0694
Rotation angle	θ	deg	3.0423	39999

Fig.45.10 rotation angle

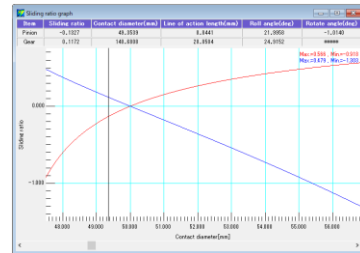


Fig.45.11 sliding ratio

45.7 Tooth surface element setting

The tooth surface element setting is shown in Fig.45.12. It sets a torque, and Young's modulus, Poisson's ratio and then the tooth profile distribution number and a pitch error with this screen. The plastic gear

can be analyzed by setting Young's modulus and Poisson's ratio. The analysis tooth profile can choose 1 tooth, 3 teeth, 5 teeth. It chooses 5 teeth when total contact ratio is big and having a pitch error. In the analysis of the example gear, it gives the pinion a 6 μ m pitch error.

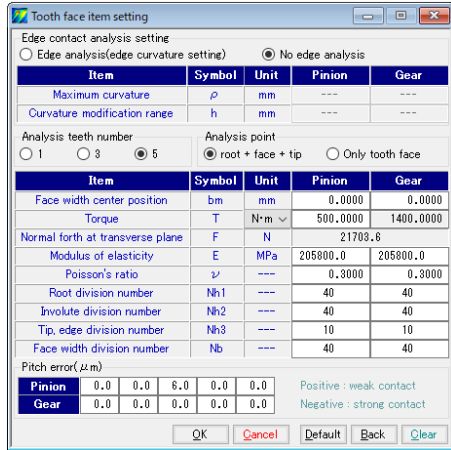


Fig.45.12 tooth surface element setting

45.8 The profile and lead modification setting

There are a profile and lead modification and three kinds (Type1-3) of the fixed form respectively. In this example, it gives the pinion a profile modification (Fig.45.13, 45.14) but a gear isn't modification.

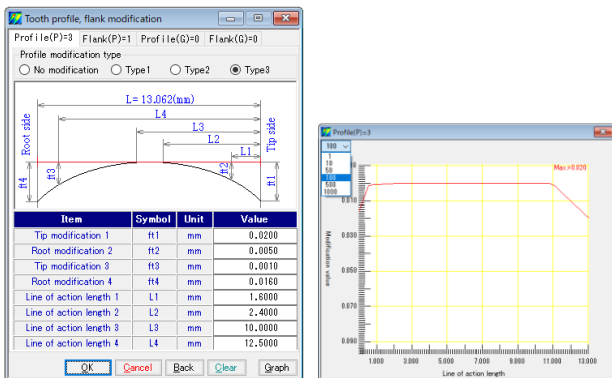


Fig.45.13 tooth modification and graph ($\times 100$)

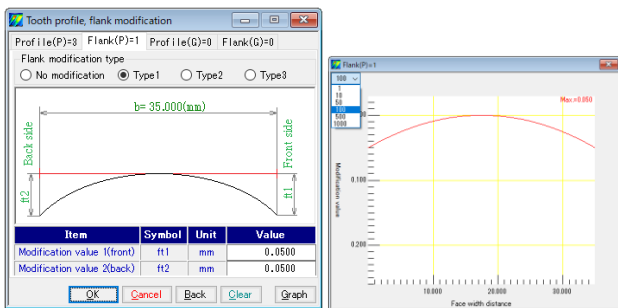
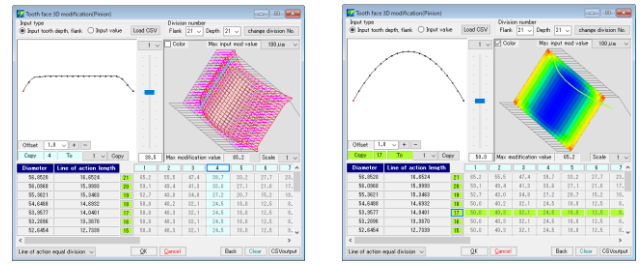


Fig.45.14 lead modification and graph ($\times 100$)

45.9 Tooth modification (3D) setting

Like Fig.45.15, the tooth surface modification (3D) can type in directly. Also, the profile modification which was set at Fig.45.13 and Fig.45.14 can be taken over, too. As for Fig.45.15, it is displaying the modification which was set at Fig.45.13 and Fig.45.14 by 3D-profile (gear is a theory tooth profile.). This tooth profile can be output by the [CSV] file. Also, this screen can read the inspection data.

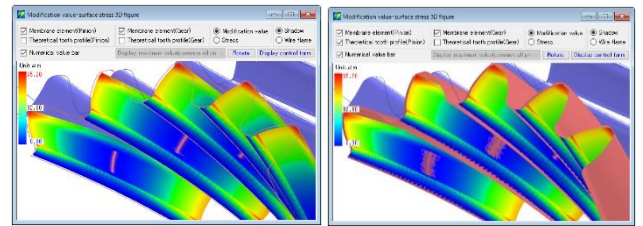


(a) Setting & profile modification (b) color palette distribution

Fig.45.15 profile modification (Ex. pinion)

45.10 Profile modification & tooth surface stress (3D)

The tooth profile which was set with the Fig.45.15 can be confirmed with 3D figure. The gear can be turned by the support form and it is possible to make it magnify a gear figure. Moreover, the contact pattern by the tooth when giving an error can be confirmed. Fig.45.16(a) is a modified tooth profile and (b) is the adjusted figure which piled a theory tooth profile on it. Also, a tooth surface element mesh model is shown to Fig.45.17.



(a) tooth modification (b) tooth modification + profile

Fig.45.16 tooth surface element

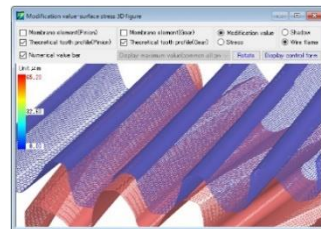


Fig.45.17 tooth surface element model (mesh / Fig.45.12)

45.11 Tooth surface stress analysis condition setting

The gear specification and torque and then, it analyzes the tooth surface stress when giving a tooth surface modification. There are two 1 angle pitch and maximum contact angle kinds of setting of an analysis angle range (Free angle can be set). It sets start angle $\theta_s = -28.578^\circ$ and end angle $\theta_e = 36.102^\circ$ like Fig.45.18 as the computation and divide that contact angle into 60. Then calculate by giving discrepancy error $\phi_1 = 0.01^\circ$ and parallelism error $\phi_2 = -0.001^\circ$. This axis angle error is the error angle when the bearing or the gear box is distorted by the load, which causes a change in the tooth contact and a change in the stress distribution.

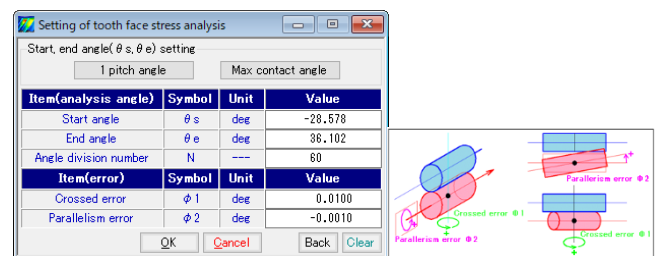
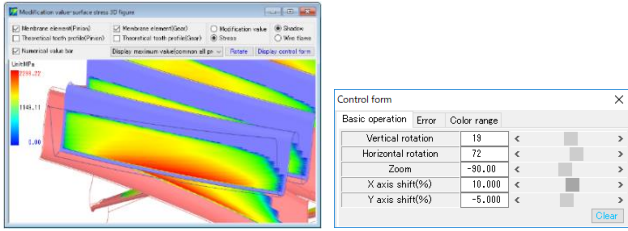


Fig.45.18 tooth surface analysis setting screen, ϕ_1 and ϕ_2

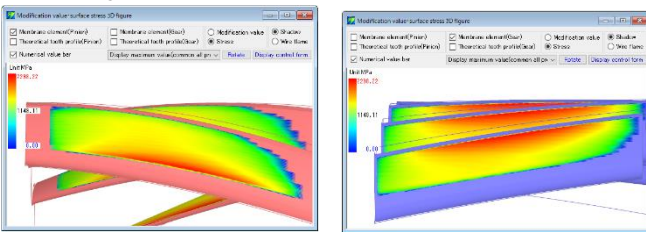
45.12 Tooth surface stress analysis result (3D diagram)

Since the pitch error is given in Fig.45.12, the tooth stress analysis result changes stress distribution depending on the tooth as shown in Fig. 45.19. However, Fig.45.20 shows the maximum stress on all teeth, so all teeth have the same stress distribution. Fig.45.21 shows the maximum and minimum of the tooth surface stress, and it can be seen that the maximum tooth surface stress is when the pinion rotation angle $\theta_p=14.177^\circ$.



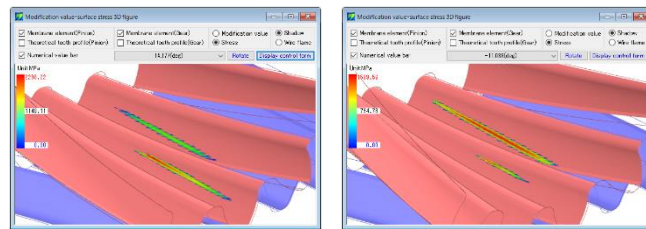
analysis result which contains a pitch-error and support form

Fig.45.19 tooth surface stress ($\sigma_{Hmax}=2298\text{MPa}$)



(a) pinion (b) gear

Fig.45.20 tooth surface stress ($\sigma_{Hmax}=2298\text{MPa}$)



(a) $\sigma_{Hmax}=2298\text{MPa}(\theta_p=14.177^\circ)$ (b) $\sigma_{Hmin}=1590\text{MPa}(\theta_p=-11.04^\circ)$

Fig.45.21 maximum and minimum value of the tooth surface stress

Fig.45.22 shows the stress distribution (cell display) of the entire tooth surface. In the case of a pinion, stress in the area of 98 in the tooth width direction (including the tooth width chamfer) and 90 in the tooth direction (including the tooth tip chamfer) is displayed, so the stress value at the tooth surface position is understood. In addition, the stress value displayed here can be output as a CSV file. As for the stress at each rotation angle, as shown in Fig. 45.23, stress distribution corresponding to pinion rotation angle can be displayed continuously, so you can grasp stress change and contact position.

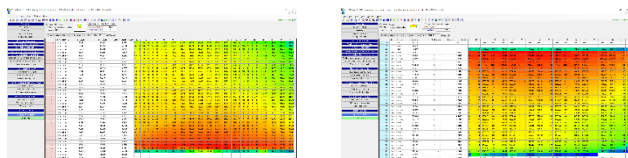


Fig.45.22 tooth surface stress ($\sigma_{Hmax}=2298\text{MPa}$)

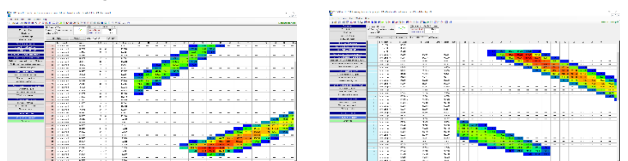


Fig.45.23 $\theta_p=14.177^\circ$ ($\sigma_{Hmax}=2298\text{MPa}$)

45.13 Flash temperature, friction coefficient, oil film thickness etc.

Fig.45.24 shows the setting screen for flash temperature calculation. Here, material (thermal conductivity) is selected in addition to the rotation speed and tooth surface roughness (Fig. 45.25). Mineral oils and synthetic oils can be selected for the type of lubricant, but in case of nonstandard, kinematic viscosity and average temperature of oil can be arbitrarily set. Calculation results of flash temperature, coefficient of friction, oil film thickness are shown in Fig.45.26 to 45.33. The probability of occurrence of scuffing and probability of wear are shown in Fig.45.34.

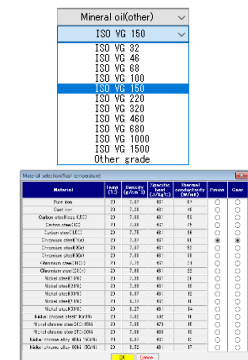
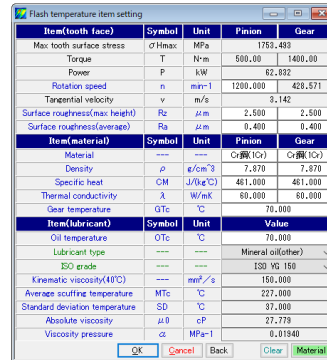
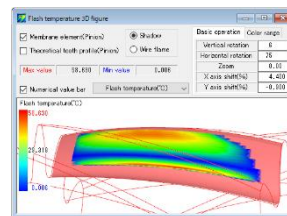


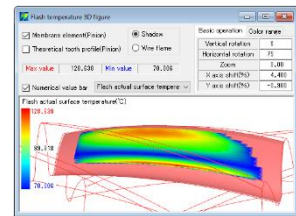
Fig.45.24 flash temperature setting

Fig.45.25 material and oil



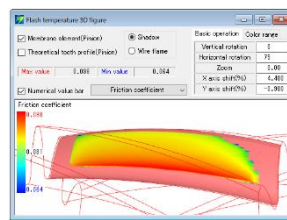
$T_{Hf}=58.6(^\circ\text{C})$

Fig.45.26 flash temperature



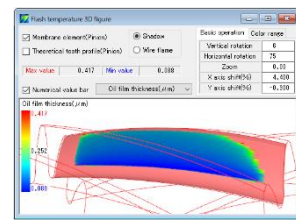
$T_{HfB}=128.6(^\circ\text{C})$

Fig.45.27 gear temperature



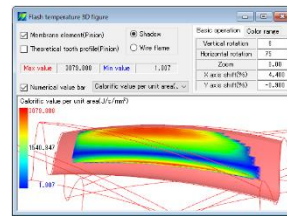
$\mu_{max}=0.098$

Fig.45.28 friction coefficient



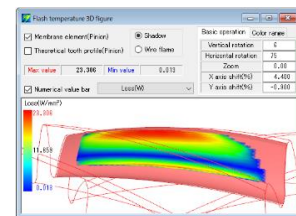
$\lambda_{min}=0.088(\mu\text{m})$

Fig.45.29 oil film thickness



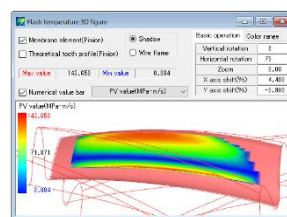
$J_{max}=3080(\text{J/s/mm}^2)$

Fig.45.30 calorific value



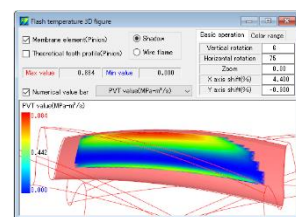
$W_{max}=23.3(\text{W/mm}^2)$

Fig.45.31 power loss



$PV_{max}=144(\text{MPa}\cdot\text{m/s})$

Fig.45.32 PV value



$PVT_{max}=0.884(\text{MPa}\cdot\text{m}^2/\text{s})$

Fig.45.33 PVT value

Item	Symbol	Unit	Value
Probability of scuffing occurrence	η_s	%	< 5
Probability of abrasion occurrence	η_f	%	25.00
Power loss	η_e	%	1.38

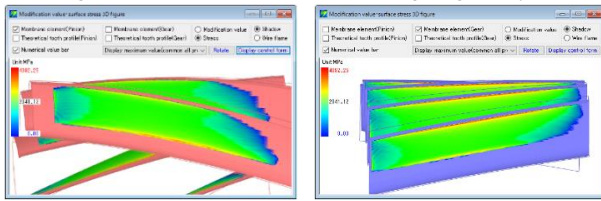
Fig.45.34 damage probability

45.14 Edge analysis (option)

In paragraphs 45.11 to 45.14, we analyzed the involute tooth surface, but here we show the result of the end analysis of the tooth tip and side part (Fig.45.35, end set at $R = 1.0$ mm). As a result of analysis, as shown in Fig.45.36, large stress $\sigma_{Hmax}=4075$ MPa is generated in pinion tooth and gear tooth tip. In the analysis of the involute tooth surface, the flash temperature is 58.5°C at the tooth tip as shown in Fig.45.26. However, in the edge analysis, it can be seen that as shown in Fig.45.37, the pinion tooth rose greatly to 182°C .

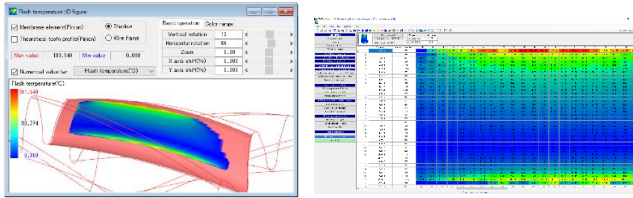
Item	Symbol	Unit	Pinion	Gear
Maximum curvature	ρ	mm	1.0000	1.0000
Curvature modification range	h	mm	1.0000	1.0000
Analysis teeth number				
Analysis point				
Face width center position	b_m	mm	0.0000	0.0000
Torque	T	N·m	500.0000	1400.0000
Normal tooth at transverse plane	F	N	21703.6	
Modulus of elasticity	E	MPa	205800.0	205800.0
Poisson's ratio	ν		0.3000	0.3000
Root division number	$Nh1$		40	40
Involute division number	$Nh2$		40	40
Tip edge division number	$Nh3$		10	10
Face width division number	Nb		40	40
Pitch error (μm)				
Pinion	0.0	0.0	0.0	0.0
Gear	0.0	0.0	0.0	0.0

Fig.45.35 tooth surface element setting (edge analysis)



(a) pinion (b) gear

Fig.45.36 tooth surface stress (edge analysis, $\sigma_{Hmax}=4082\text{MPa}$)



(a) tooth profile (b) cell

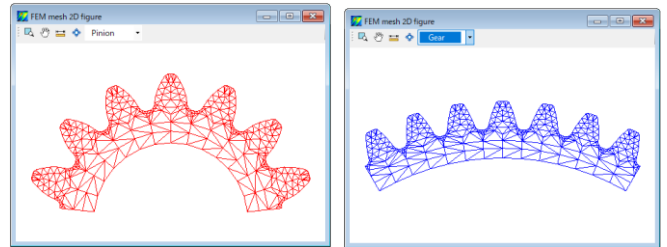
Fig.45.37 flash temperature, $T_f=182^\circ\text{C}$

45.15 FEM analysis

In the analysis condition of Fig.45.12, to make FEM analysis, create a mesh model in Fig.45.38. Here we create a mesh with the standard model, but there are two ways of setting, one is to determine the tooth profile with accuracy and the other is to determine the tooth profile by the number of divisions. The meshed tooth profile can be confirmed with the 2D mesh model as shown in Fig. 45.39. Also, 3D-FEM mesh elements can display the number of elements and the number of nodes as shown in Fig.45.40 and the node coordinates as shown in Fig.45.41.

Item	Symbol	Unit	Pinion	Gear
Root division number	NL1	---	5	5
Surface division number	NL2	---	5	5
Tip division number	NL3	---	3	3
Side division number	hNO	---	5	5
Bottom division number	wNO	---	15	15
Bottom diameter	dm	mm	30.4520	116.8256
Division number of specified range	N	---	20	20
Diameter of specified range	dq1	mm	46.6316	143.2256
Diameter of specified range	dq2	mm	40.9520	127.3256

Fig.45.38 mesh model setting



(a) pinion (b) gear

Fig.45.39 2D-mesh model

Item	Symbol	Unit	Pinion	Gear
Max contact stress/membrane element stress	σ_P	MPa	2298.22	
Element number			6403	6395
Node number			16676	89927
Max bending stress (σ_1)	σ_1	MPa	---	---
Max bending element No.			---	---

Fig.45.40 FEM element

Node No.	X	Y	Z
1	-29.226	1.067	-15.441
2	-29.226	-0.868	-17.117
3	-29.226	-2.960	-15.204
4	-29.226	-0.875	-17.530
5	-29.226	1.978	-16.444
6	-29.226	-1.969	-15.119
7	-29.226	1.897	-17.530
8	-29.226	1.069	-16.226
9	-29.226	-1.162	-16.536
10	-29.226	1.188	-16.208
11	-29.226	-1.152	-16.333
12	-29.226	0.126	-17.117
13	-29.226	1.138	-16.471

Fig.45.41 element nod table

The mesh model can be generated as a rim / hub model as shown in Fig.45.42, so it is effective for gears with low elastic modulus like plastic gears.

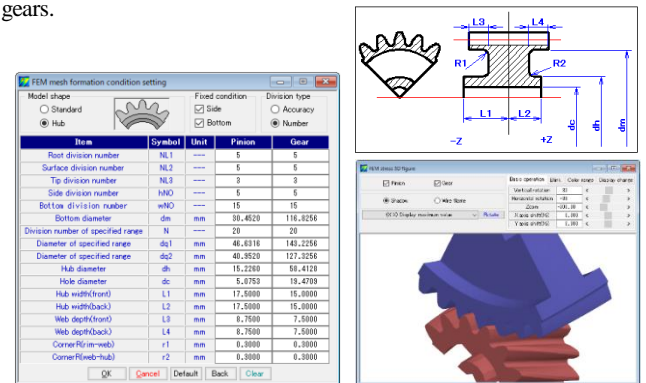


Fig.45.42 rim / hub model

Next, an example of FEM analysis using the mesh model set in Fig. 45.38 is explained below. Set the angle (-28.578° to 36.102°) set in the tooth surface analysis setting in Fig. 45.18 as shown in Fig. 45.43 (angle skipping selection) FEM analysis. The check of also includes the angle of $\theta_P = 14.177^\circ$ (Fig.45.21) with the largest tooth surface stress. Also, analyzing all 60 divisions will consume memory and time, so it is effective to select only the required meshing angle and calculate.

The items analyzed by FEM are the stress, displacement and strain shown in Fig.45.44. FEM analysis results are shown in Fig.45.45 to 45.49. The displacement chart can be displayed at 100 times (magnification selection: 1, 5, 10, 50, 100, 200, 500 times) as shown in Fig.45.48.

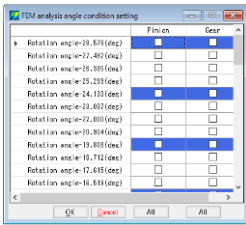


Fig.45.43 FEM analysis choice

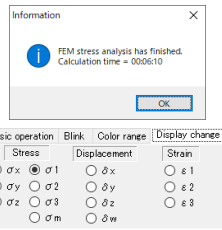
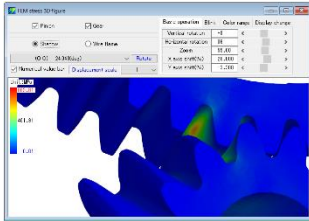
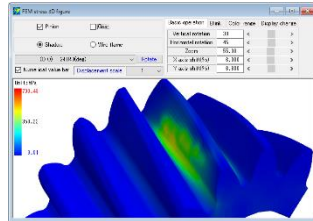


Fig.45.44 kind of the analysis

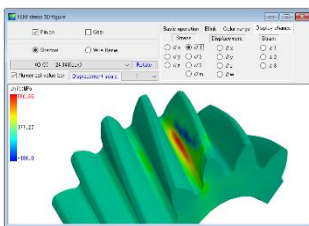


(a) one pair gear

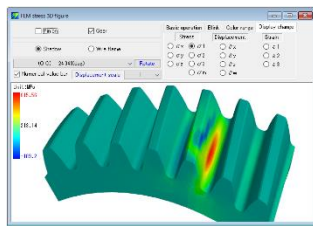


(b) pinion, $\sigma_{\text{max}}=837\text{MPa}$

Fig.45.45 σ_m (Mises stress), $\theta_p=24.043^\circ$

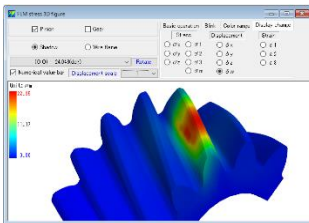


(a) pinion, $\sigma_{1\text{max}}=551\text{MPa}$

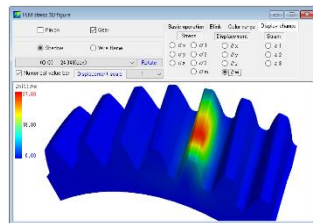


(b) gear, $\sigma_{1\text{max}}=616\text{MPa}$

Fig.45.46 maximum principal stress, $\theta_p=24.043^\circ$

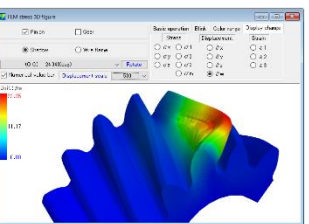


(a) pinion, $\delta_{\text{max}}=22.4\mu\text{m}$

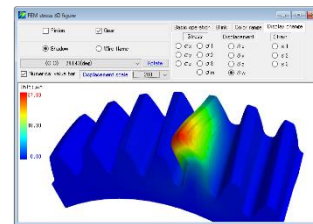


(b) gear, $\delta_{\text{max}}=37.8\mu\text{m}$

Fig.45.47 displacement, $\theta_p=24.043^\circ$

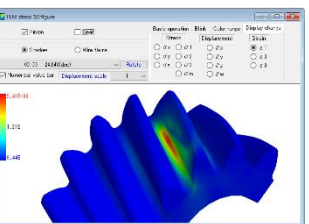


(a) pinion, $\times 500$

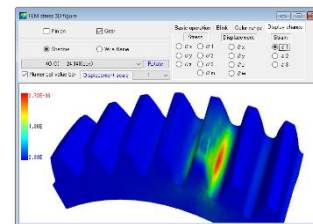


(b) gear, $\times 200$

Fig.45.48 displacement (zoom), $\theta_p=24.043^\circ$



(a) pinion, $\epsilon_{1\text{max}}=2.41 \times 10^{-3}$



(b) gear, $\epsilon_{1\text{max}}=2.72 \times 10^{-3}$

Fig.45.49 distortion, $\theta_p=24.043^\circ$

In Fig.45.43, we analyze the pinion rotation angle as $\theta_p = -28.578$ to 36.102 (Fig.45.18). When we summarize this, we can see that since the pitch error (Fig. 45.12, $6 \mu\text{m}$) is given as shown in Fig.45.50, the

dedendum stress greatly changes. In Fig. 45.50, the angle showing the maximum value is $\theta_p = 19.665^\circ$, and its maximum stress is $\sigma_{1\text{max}}(P) = 551\text{MPa}$ and $\sigma_{1\text{max}}(G) = 617\text{MPa}$. An analysis list at this angle is shown in Fig.45.51.

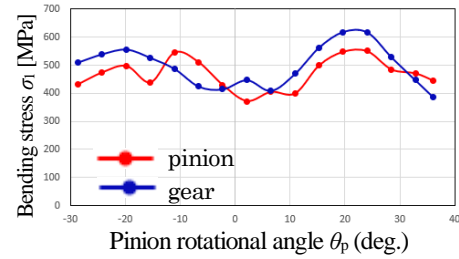


Fig.45.50 change of the fillet stress ($\sigma_{1\text{max}}$)

Element No.	Element Type	Element stress (MPa)	Node displacement (mm)	Node displacement (mm)	Node displacement (mm)	Min. stress P	Min. stress G
1	2	2.14	-0.01	0.04	0.04	1.02	0.12
2	2	1.88	-0.01	0.03	0.03	0.94	0.10
3	2	1.67	-0.01	0.02	0.02	0.83	0.09
4	2	1.47	-0.01	0.01	0.01	0.73	0.08
5	2	1.28	-0.01	0.00	0.00	0.64	0.07
6	2	1.10	-0.01	0.00	0.00	0.56	0.06
7	2	0.94	-0.01	0.00	0.00	0.48	0.05
8	2	0.80	-0.01	0.00	0.00	0.41	0.04
9	2	0.68	-0.01	0.00	0.00	0.35	0.03
10	2	0.58	-0.01	0.00	0.00	0.29	0.02
11	2	0.50	-0.01	0.00	0.00	0.25	0.02
12	2	0.43	-0.01	0.00	0.00	0.21	0.01
13	2	0.38	-0.01	0.00	0.00	0.18	0.01
14	2	0.34	-0.01	0.00	0.00	0.16	0.01
15	2	0.31	-0.01	0.00	0.00	0.15	0.01
16	2	0.28	-0.01	0.00	0.00	0.14	0.01
17	2	0.26	-0.01	0.00	0.00	0.13	0.01
18	2	0.24	-0.01	0.00	0.00	0.12	0.01
19	2	0.23	-0.01	0.00	0.00	0.11	0.01
20	2	0.22	-0.01	0.00	0.00	0.11	0.01

Fig.45.51 analysis result list

It is understood that the element number of the maximum value $\sigma_{1\text{max}}=551$ MPa of the maximum principal stress of the pinion in the analysis result list is 37766. If you enter this number in "blinking" in Fig.45.52, you can check with the stress distribution map (▲ flashes in ○). After completion of FEM analysis, stress at any position in the tooth width direction can be displayed as shown in Fig. 45.53. Fig.45.53 shows the stress distribution at the tooth width center section position ($z=0$ mm). For reference, Fig.45.54 shows the tooth root stress distribution in the analysis angle range.

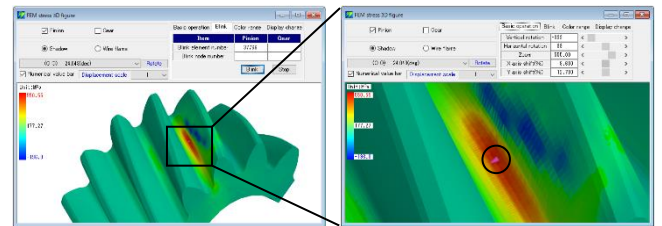
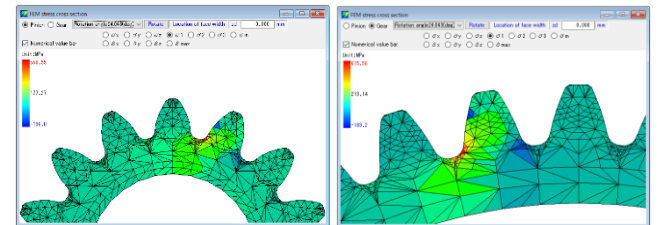


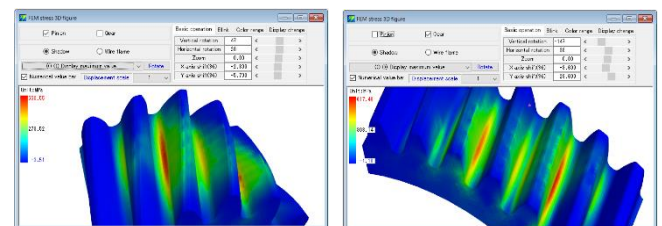
Fig.45.52 pinion, $\sigma_{1\text{max}}$ point, $\sigma_{1\text{max}}=555\text{MPa}$



(a) pinion, $\sigma_{1\text{max}}=551\text{MPa}$

(b) gear, $\sigma_{1\text{max}}=616\text{MPa}$

Fig.45.53 FEM-section ($z=0\text{mm}$)



(a) ピニオン $\sigma_{1\text{max}}=551\text{MPa}$

(b) ギヤ $\sigma_{1\text{max}}=616\text{MPa}$

Fig.45.54 fillet stress in the analysis angle range

45.16 Lifetime

Calculate lifetime after tooth surface stress analysis and FEM analysis. Fig.45.55 shows the lifetime when the allowable stress value for material's tooth surface strength is $\sigma_{Hlim}=2000$ MPa and the allowable stress value for bending strength is $\sigma_{Flim}=400$ MPa.

Lifetime calculation					
Item	Symbol	Unit	Pinion	Gear	
Max contact stress	σ_{Hmax}	MPa	2241.093	2236.216	
Max bending stress(σ^1)	σ^1	MPa	850.845	817.457	
Rotation speed	n	r/min	1200.000	428.571	
Allowable Hertzian stress	σ_{Hlim}	MPa	2000.000	2000.000	
Allowable bending stress	σ_{Flim}	MPa	400.000	400.000	
Overload cycles	---	---	---	---	
Nitride material	---	---	No nitride material	---	
use condition	---	---	Normal	---	
Item(contact)	Symbol	Unit	Pinion	Gear	
Expected stress repeat factor	ZN'	---	1.121	1.149	
Expected lifespan load number	Nc	---	1.31E+06	8.36E+05	
Expected lifespan	Lc	hrs	1.82E+01	3.25E+01	
Item(bending)	Symbol	Unit	Pinion	Gear	
Expected stress repeat factor	ZN'	---	1.376	1.544	
Expected lifespan load number	Nc	---	2.85E+05	1.09E+05	
Expected lifespan	Lc	hrs	3.96E+00	4.24E+00	

Fig.45.55 lifetime

45.17 Transmission error (option)

Fig.45.56 shows the rotation transmission error within the rotation angle given in the tooth surface analysis setting screen, and Fig.45.57 shows the Fourier analysis result.

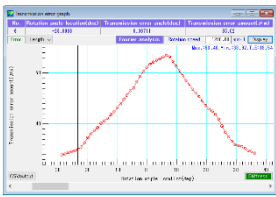


Fig.45.56 transmission error

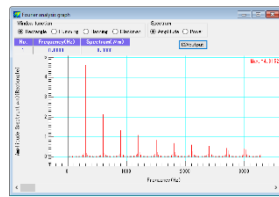


Fig.45.57 Fourier analyses

45.18 Analysis of optimal tooth surface modification

As shown in Fig. 45.14, instead of uniformly determining the tooth surface modification, it is a function that can determine the amount of correction that minimizes tooth surface stress when considering torque, pitch error, and shaft angle error. It is possible to reduce the tooth surface stress generated by applying appropriate tooth surface modification.

As an example, Fig. 45.4 When the torque of Fig. 45.58 is applied with the gear and the discrepancy error of the shaft is set to $\phi_1 = 0.01^\circ$ and the parallelism error is set to $\phi_2 = -0.001^\circ$ as shown in Fig. 45.59, when the modification distribution ratio is set to 0.5, You can obtain tooth surface modification like 45.60 (finely adjusted tooth surface shape generated by optimal tooth surface modification). Fig.45.61 to 45.65 calculate the tooth surface stress, flash temperature, friction coefficient, etc. based on this tooth surface modification, the tooth root stress is shown in Fig.45.67, and the life time is shown in Fig.45.68.

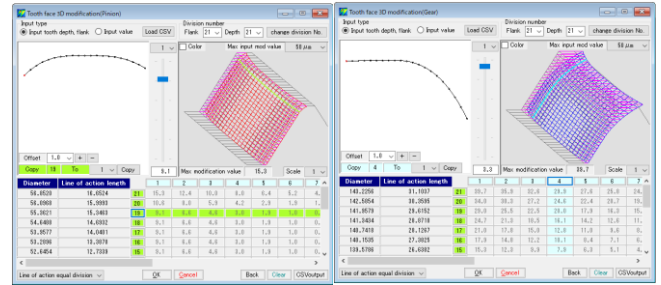
As a result, since the tooth surface stress decreases from $\sigma_{Hmax}=2295$ MPa (Fig. 45.20) to $\sigma_{Hmax}=1637$ MPa, the life time to the tooth surface has also been dramatically extended.

Item	Symbol	Unit	Pinion	Gear	
Maximum curvature	ρ	mm	---	---	
Curvature modification range	n	mm	---	---	
Analysis tooth number	---	---	---	---	
Analysis point	---	---	---	---	
Item	Symbol	Unit	Pinion	Gear	
Face width center position	b _m	mm	0.0000	0.0000	
Torsion	T	Nm	500.0000	1400.0000	
Normal tooth of transverse plane	F	N	2193.0	---	
Modulus of elasticity	E	MPa	205000.0	205000.0	
Poisson's ratio	ν	---	0.3000	0.3000	
Root division number	N _{R1}	---	40	40	
Pinion division number	N _{P1}	---	40	40	
Tip edge division number	N _{T1}	---	10	10	
Face width division number	N _B	---	40	40	

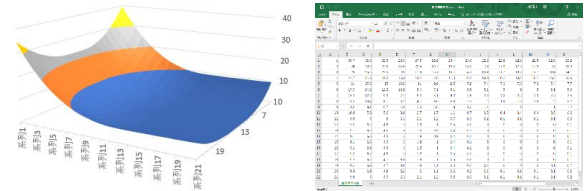
Fig.45.58 torque setting

Item	Symbol	Unit	Pinion	Gear	
Correction error	ϕ_1	deg	0.0100	---	
End face deviation (E to end I)	ϕ_2	mm	0.0001	---	
Parallelism error	ϕ_3	mm	-0.0010	---	
Tip interference amount (E to end ϕ_2)	ϕ_4	mm	-0.0005	---	
Tip edge division number	N	---	6	---	
Item	Symbol	Unit	Pinion	Gear	
Frequency of Hertzian calculation	η	---	0.5000	0.5000	
Modification value (mm)	He	mm	0.0001	0.0001	
Modification value (μm)	Hc	mm	0.0001	0.0001	
Modification value (mm)	He	mm	0.0050	0.0050	
Modification value (μm)	Hc	mm	0.0050	0.0050	
Modification ratio (mm)	He	mm	0.0010	0.0010	
Modification ratio (μm)	Hc	mm	0.0010	0.0010	
Modification ratio (mm)	He	mm	0.0010	0.0010	
Modification ratio (μm)	Hc	mm	0.0010	0.0010	

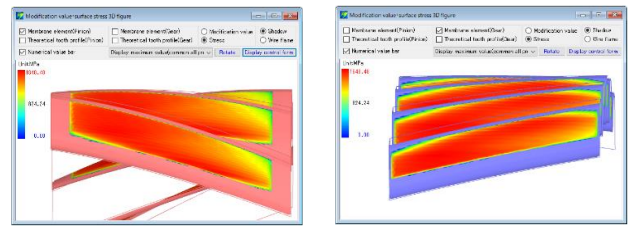
Fig.45.59 modification setting



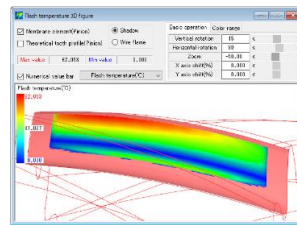
(a) pinion (b) gear
Fig.45.60 optimal tooth surface modification



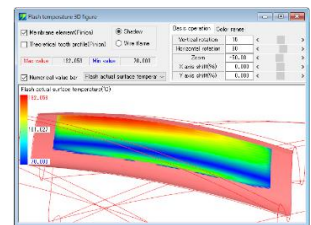
[csv] output, Fig.45.60(b)
Fig.45.61 optimal tooth surface modification (Excel)



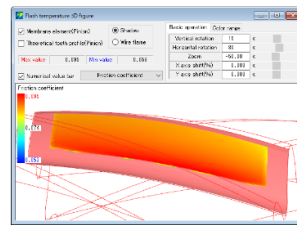
(a) pinion (b) gear
Fig.45.62 tooth surface stress ($\sigma_{Hmax}=1648$ MPa)



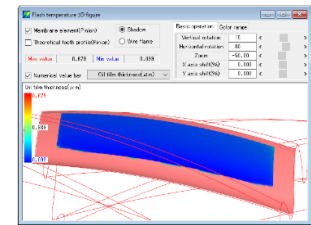
$T_{fP}=62.1(^{\circ}C)$
Fig.45.63 flash temperature



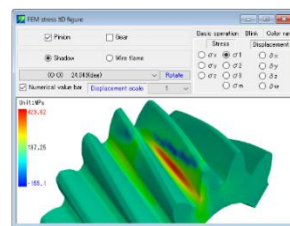
$T_{fB}=132(^{\circ}C)$
Fig.45.64 gear temperature



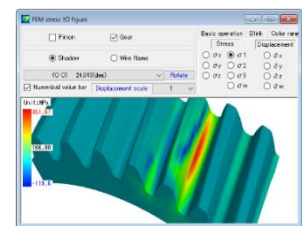
$\mu_{max}=0.095$
Fig.45.65 friction coefficient



$\lambda_{min}=0.099(\mu m)$
Fig.45.66 oil film thickness



(a) pinion, $\sigma_{1max}=430$ MPa



(b) gear, $\sigma_{1max}=452$ MPa

Fig.45.67 maximum principal stress, $\theta_p=24.043^{\circ}$

Item	Symbol	Unit	Pinion	Gear
Max contact stress	σ_{Hmax}	MPa	1640.774	1648.484
Max bending stress (σ_1)	σ_1	MPa	600.867	537.820
Rotation speed	n	1/min	1200.000	428.571
Allowable Hertzian stress	σ_{Hlim}	MPa	2000.000	2000.000
Allowable bending stress	σ_{Flim}	MPa	400.000	400.000
Overload cycles	Ne	---	---	1
Nitride material	---	---	No nitride material	
use condition	---	---	Normal	
Item(contact)	Symbol	Unit	Pinion	Gear
Expected stress repeat factor	ZN	---	0.820	0.824
Expected lifespan load number	Nc	---	1.00E+10	1.00E+10
Expected lifespan	Lc	hrs	1.38E+05	3.89E+05
Item(bending)	Symbol	Unit	Pinion	Gear
Expected stress repeat factor	ZN	---	1.502	1.344
Expected lifespan load number	Nc	---	1.37E+05	3.48E+05
Expected lifespan	Lc	hrs	1.80E+00	1.85E+01

Fig.45.68 lifetime

45.19 Analysis of the internal-gear (option)

The analysis result of "external gear × internal gear" is shown Fig.45.69 to 45.84.

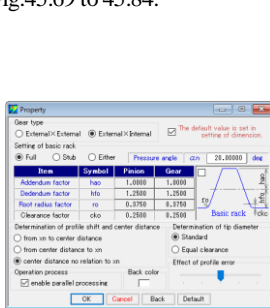


Fig.45.69 basic rack

Item	Symbol	Unit	Pinion	Gear
Number of teeth	Z	---	15	55
Normal pressure angle	α_n	deg	25	25.00000
Helix angle	β	deg	0	0.00
Helix direction	---	---	Right hand	Right hand
Reference diameter	d	mm	48.85201	182.65736
Base diameter	db	mm	46.87932	188.84283
Input type of tooth thickness	---	---	Profile shift coefficient	Profile shift coefficient
Normal profile shift coefficient	xn	---	0.20000	0.20000
Number of teeth spanned	zm	---	3	3
Base tangent length	Wb	mm	23.59828	78.74851
Ball diameter	db	mm	5.00000	5.0201
Over ball distance	dbd	mm	59.28308	178.42784
Normal circular tooth thickness	S _n	mm	5.38754	4.27562
Center distance	a	mm	8.20000	85.80000
Tooth thickness for backlash	s	mm	30.30000	30.30000
Face width	b	mm	57.42000	177.25740
Tip diameter	da	mm	42.36500	186.37480
Root diameter	df	mm	1.12500	1.12500
Root radius(rod tip radius)	rt	mm	1.12500	1.12500

Fig.45.70 gear specification

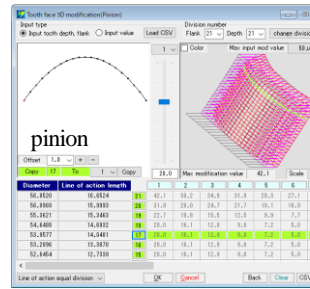


Fig.45.76 profile modification

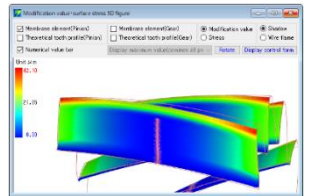
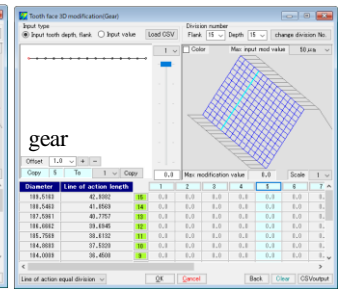


Fig.45.77 tooth surface element

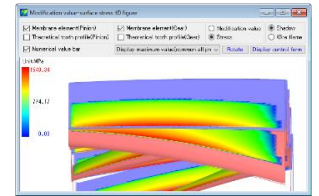


Fig.45.78 $\sigma_{Hmax}=1548MPa$

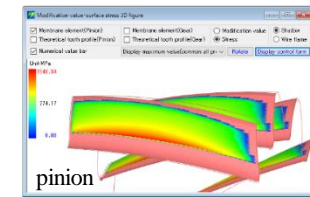


Fig.45.79 tooth surface stress ($\sigma_{Hmax}=1548MPa$)

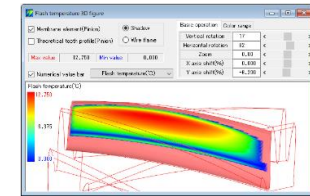
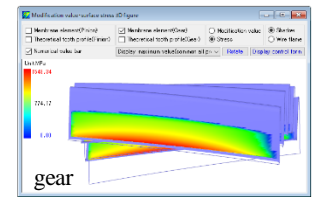


Fig.45.80 flash temperature

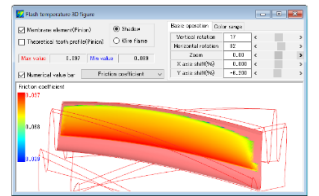


Fig.45.81 friction coefficient

Item	Symbol	Unit	Pinion	Gear
Transverse module	mt	mm	3.31013	---
Transverse pressure angle	α_{t1}	deg	21.89923	---
Base helix angle	β_b	deg	---	---
Lead	lx	mm	334.5138	1228.5608
Profile shift coefficient	xm	---	0.80000	0.80000
Tooth depth	h	mm	6.75000	6.75000
Min involute diameter(TIP)	dt	mm	46.43116	177.8574
Max involute diameter	dm	mm	56.85208	185.1163
Transverse pitch	ptd	mm	3.55000	---
Transverse circular tooth thickness	st	mm	5.32224	4.7176
Number of teeth spanned	zm	---	3	3
Base tangent length(Reference)	Wb	mm	23.59828	78.74851
Base tangent length(Design)	W	mm	23.59828	78.74851
Over ball diameter	dbd	mm	5.00000	5.0201
Over ball diameter(Reference)	dbm	mm	59.28308	178.42784
Over ball diameter(Design)	dbd	mm	59.28322	178.42783

Fig.45.71 dimension result-1

Item	Symbol	Unit	Pinion	Gear
Transverse contact middle	dmtd	deg	16.28144	---
Contact helix angle	β_w	deg	24.00000	---
Contact pitch diameter	dm	mm	48.75000	178.7500
Teeth number ratio	z _h	---	3.6667	0.2727
Effective face width	b _h	mm	38.0000	---
Clearance	ck	mm	1.6527	1.6527
Transverse contact ratio	α_{ct}	---	1.5462	---
Total contact ratio	α_{Σ}	---	2.3884	---
Sliding ratio(rod)	sr	---	-9.1948	-8.6118
Sliding ratio(tip)	sr _t	---	8.2785	8.1033
Backlash angle	J β	deg	1.44000	0.42000
Overlash ratio	o _r	---	4.68	---
Contact diameter(rod)	dmr	mm	86.8028	186.1819
Contact diameter(tip)	dmr _t	mm	42.3180	177.8574
Involute interference	---	---	not occur	---
Trimming	---	---	not occur	---
Trusthead interference	---	---	not occur	---
Flute(s) interference	---	---	not occur	---

Fig.45.72 dimension result-2

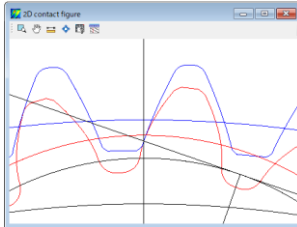


Fig.45.73 meshing drawing

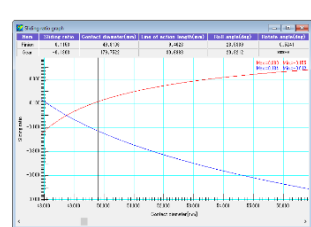
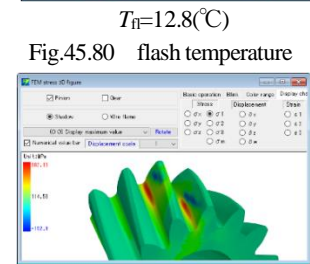


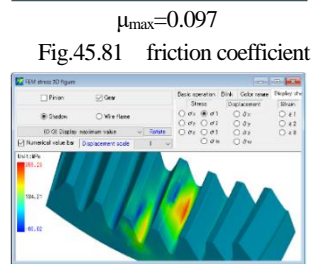
Fig.45.74 sliding ratio

Item	Symbol	Unit	Pinion	Gear
Maximum curvature	ρ	mm	---	---
Curvature modification range	h	mm	---	---
Analysis teeth number	---	---	1	5
Analysis point	---	---	root + face + tip	Only tooth face
Item	Symbol	Unit	Pinion	Gear
Face width center position	bm	mm	0.0000	0.0000
Torque	T	Nmm	600.0000	1838.3333
Normal force at transverse plane	F	N	21789.8	---
Modulus of elasticity	E	MPa	205000.0	205000.0
Poisson's ratio	ν	---	0.30000	0.30000
Root division number	Nh1	---	40	10
Involute division number	Nh2	---	40	40
Tip, edge division number	Nh3	---	10	40
Face width division number	Nb	---	40	40
Pitch error (μm)	---	---	---	---
Pinion	0.0	0.0	0.0	0.0
Gear	0.0	0.0	0.0	0.0

Fig.45.75 tooth surface element setting



(a) pinion, $\sigma_{1max}=382MPa$



(b) gear, $\sigma_{1max}=355MPa$

Fig.45.82 maximum principal stress,

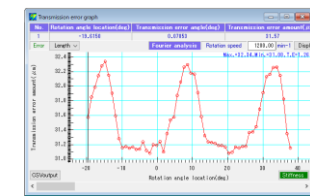


Fig.45.83 transmission error

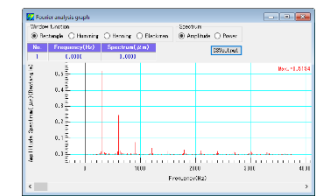


Fig.45.84 Fourier analyses

- ※1 The tooth shape given in Fig.45.15 and the tooth profile generated by optimal tooth surface modification can be file output (3D-IGES), so it can be used for analysis and processing.
- ※2 Please see Appendix [I] for stress analysis examples, Appendix [J] for transmission error analysis examples and Appendix [K] for examples of power loss analysis.